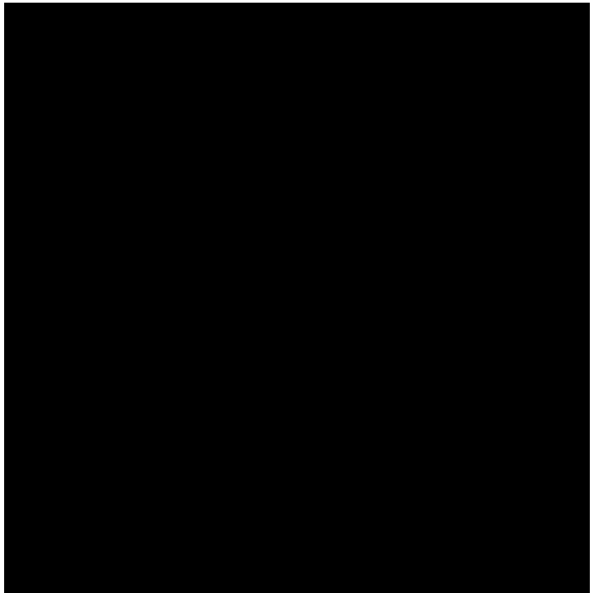


EXERCISE 23

POINTS-TO ANALYSIS REVIEW

Write your name and answer the following on a piece of paper

Draw the points-to graph of the following snippet:



Assignment	Constraint
$a = \&b$	$a \supseteq \{ b \}$
$a = b$	$a \supseteq b$
$a = *b$	$a \supseteq *b$
$*a = b$	$*a \supseteq b$

EXERCISE 23 SOLUTION

POINTS-TO ANALYSIS REVIEW

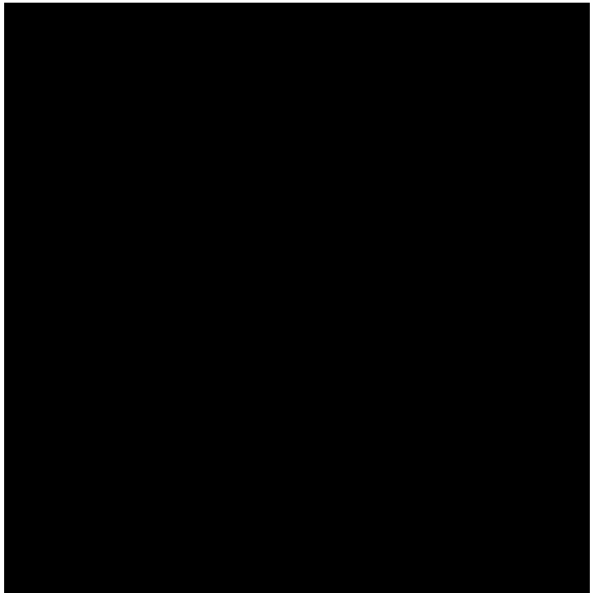
Assignment	Constraint
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EXERCISE 23

POINTS-TO ANALYSIS REVIEW

Write your name and answer the following on a piece of paper

Draw the points-to graph of the following snippet:

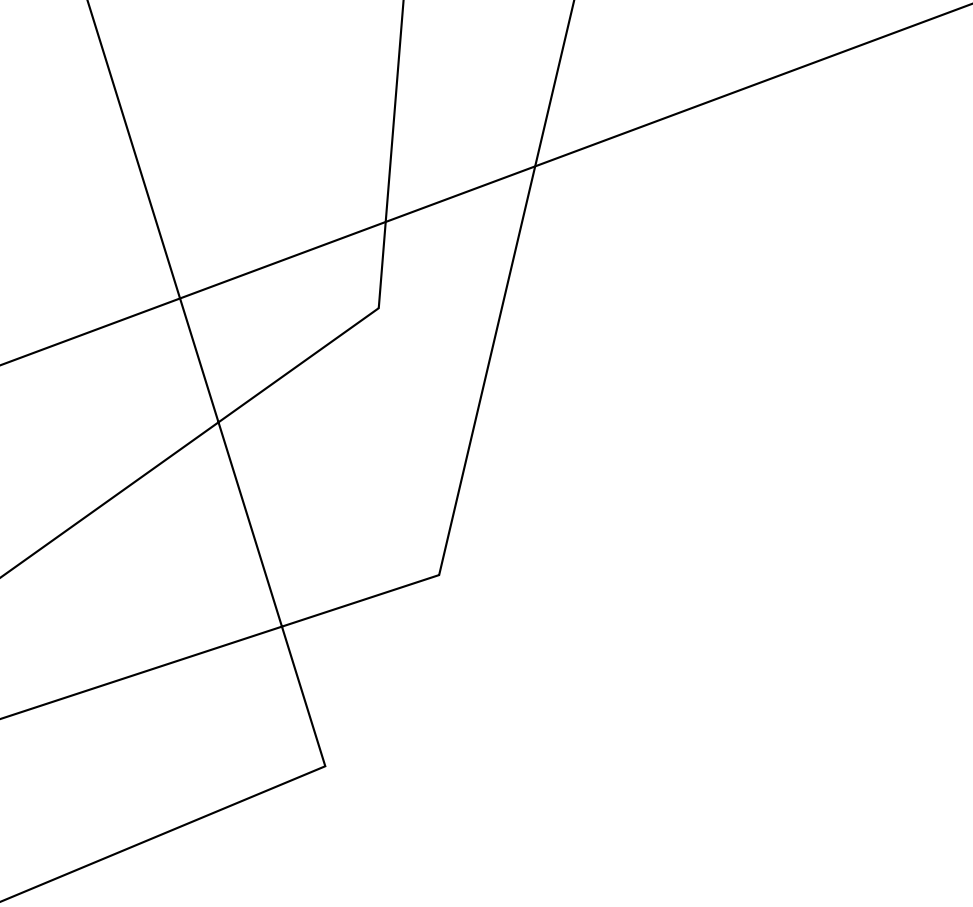


Assignment	Constraint
$a = \&b$	$a \supseteq \{ b \}$
$a = b$	$a \supseteq b$
$a = *b$	$a \supseteq *b$
$*a = b$	$*a \supseteq b$

EXERCISE 23 SOLUTION

POINTS-TO ANALYSIS REVIEW

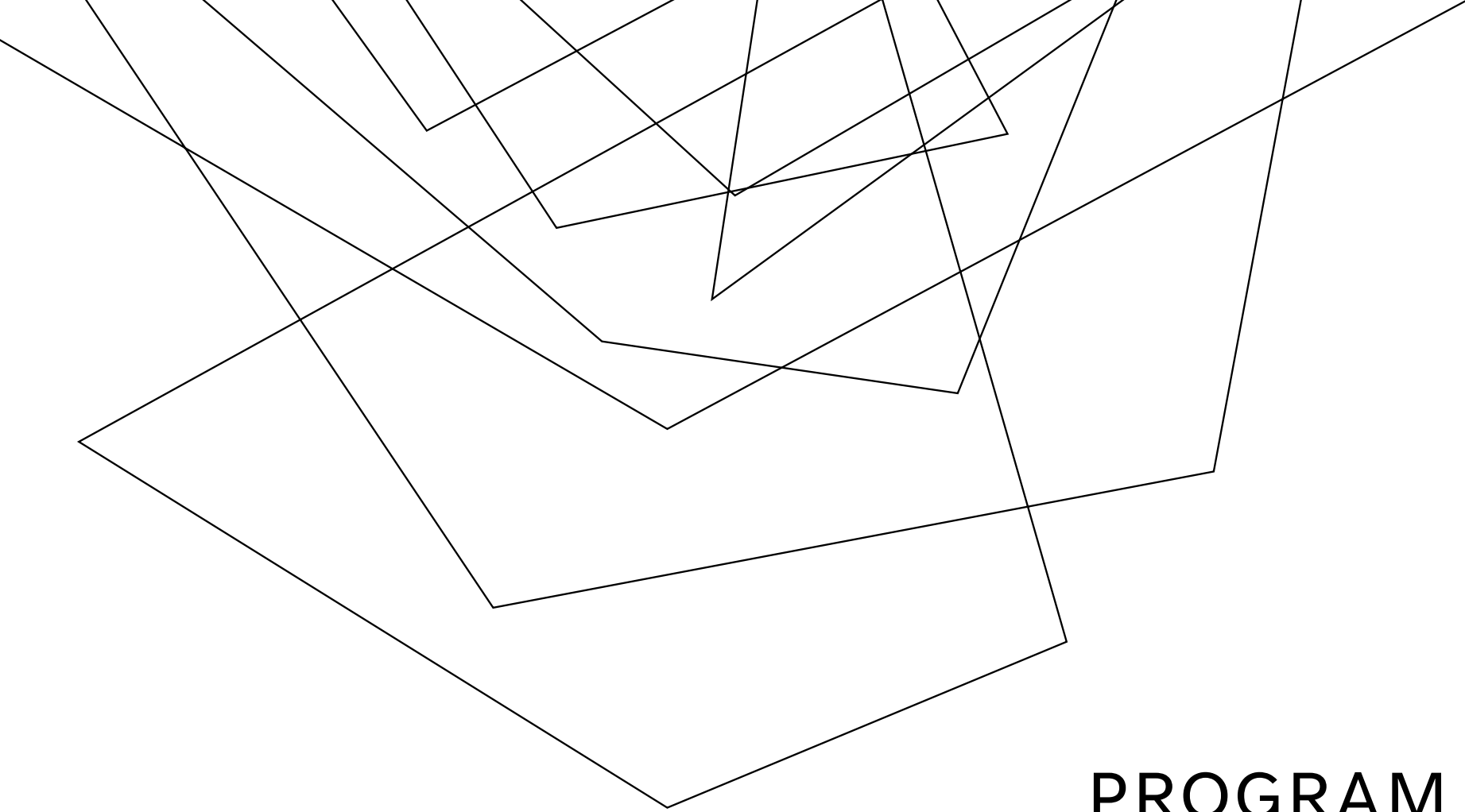
Assignment	Constraint
$a = \&b$	$a \supseteq \{ b \}$
$a = b$	$a \supseteq b$
$a = *b$	$a \supseteq *b$
$*a = b$	$*a \supseteq b$

Abstract geometric lines in the top-left corner of the slide, consisting of several thin black lines forming a series of overlapping triangles and polygons.

Quiz 2 on Monday

Review session: Friday at 6:30 PM, Location TBA

**ADMINISTRIVIA
AND
ANNOUNCEMENTS**

Abstract geometric lines in the top-left corner of the slide, consisting of several thin black lines forming overlapping, irregular polygons and triangles.

PROGRAM INSTRUMENTATION

EECS 677: Software Security Evaluation

Drew Davidson

ANDERSEN'S ALGORITHM

REVIEW: LAST LECTURE

REACHABILITY FORMULATION

Step 1: Extract pointer-related operations

Step 2: Saturate points-to graph

Step 3: Compute node reachability

Assignment	Constraint	Meaning
$a = \&b$	$a \supseteq \{b\}$	$\text{loc}(b) \in \text{pts}(a)$
$a = b$	$a \supseteq b$	$\text{pts}(a) \supseteq \text{pts}(b)$
$a = *b$	$a \supseteq *b$	$\forall v \in \text{pts}(b). \text{pts}(a) \supseteq \text{pts}(v)$
$*a = b$	$*a \supseteq b$	$\forall v \in \text{pts}(a). \text{pts}(v) \supseteq \text{pts}(b)$

ANDERSEN'S ALGORITHM: REACHABILITY

REVIEW: LAST LECTURE

REACHABILITY FORMULATION

Step 1: List pointer-related operations

Step 2: Saturate points-to graph

Step 3: Compute node reachability

Assignment	Constraint	Meaning
$a = \&b$	$a \supseteq \{b\}$	$\text{loc}(b) \in \text{pts}(a)$
$a = b$	$a \supseteq b$	$\text{pts}(a) \supseteq \text{pts}(b)$
$a = *b$	$a \supseteq *b$	$\forall v \in \text{pts}(b). \text{pts}(a) \supseteq \text{pts}(v)$
$*a = b$	$*a \supseteq b$	$\forall v \in \text{pts}(a). \text{pts}(v) \supseteq \text{pts}(b)$

Program

$p = \&a$

$p = \&b$

$m = \&p;$

$r = *m;$

$q = \&c;$

$m = \&q$

Constraints

$p \supseteq \{a\}$

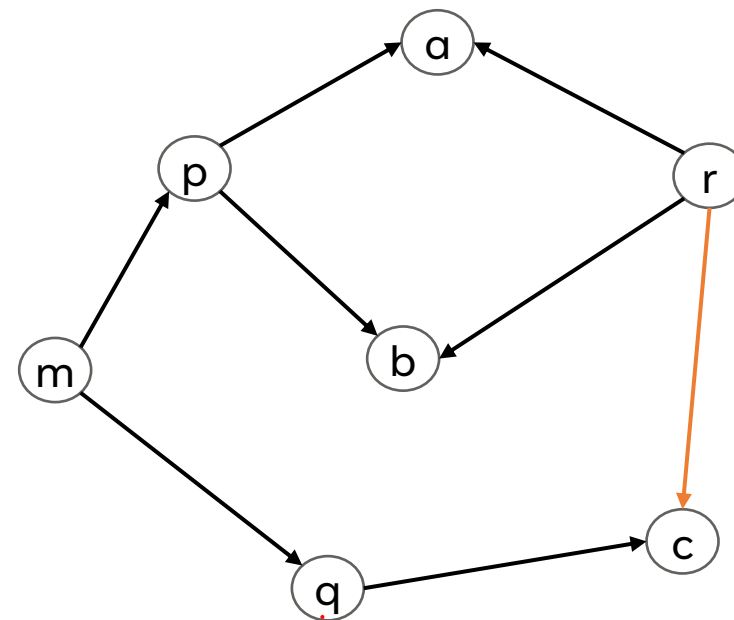
$p \supseteq \{b\}$

$m \supseteq \{p\}$

$r \supseteq *m$

$q \supseteq \{c\}$

$m \supseteq \{q\}$



Initial

$\text{pts}(a) = \{ \}$

$\text{pts}(b) = \{ \}$

$\text{pts}(m) = \{ \}$

$\text{pts}(p) = \{ \}$

$\text{pts}(q) = \{ \}$

$\text{pts}(r) = \{ \}$

Final

$\text{pts}(a) = \{ \}$

$\text{pts}(b) = \{ \}$

$\text{pts}(m) = \{ p, q \}$

$\text{pts}(p) = \{ a, b \}$

$\text{pts}(q) = \{ c \}$

$\text{pts}(r) = \{ a, b, c \}$

POINTS TO AND TYPE SAFETY

REVIEW: LAST LECTURE

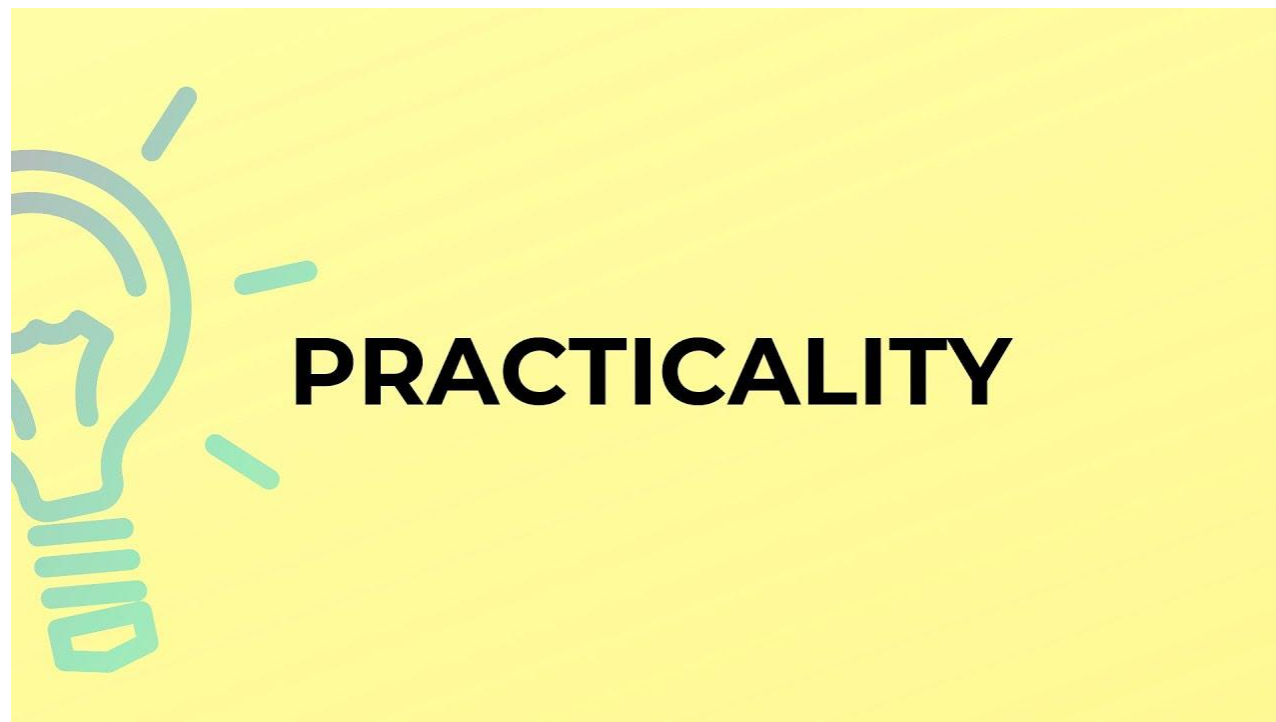
A “FEATURE” OF THE ANALYSIS

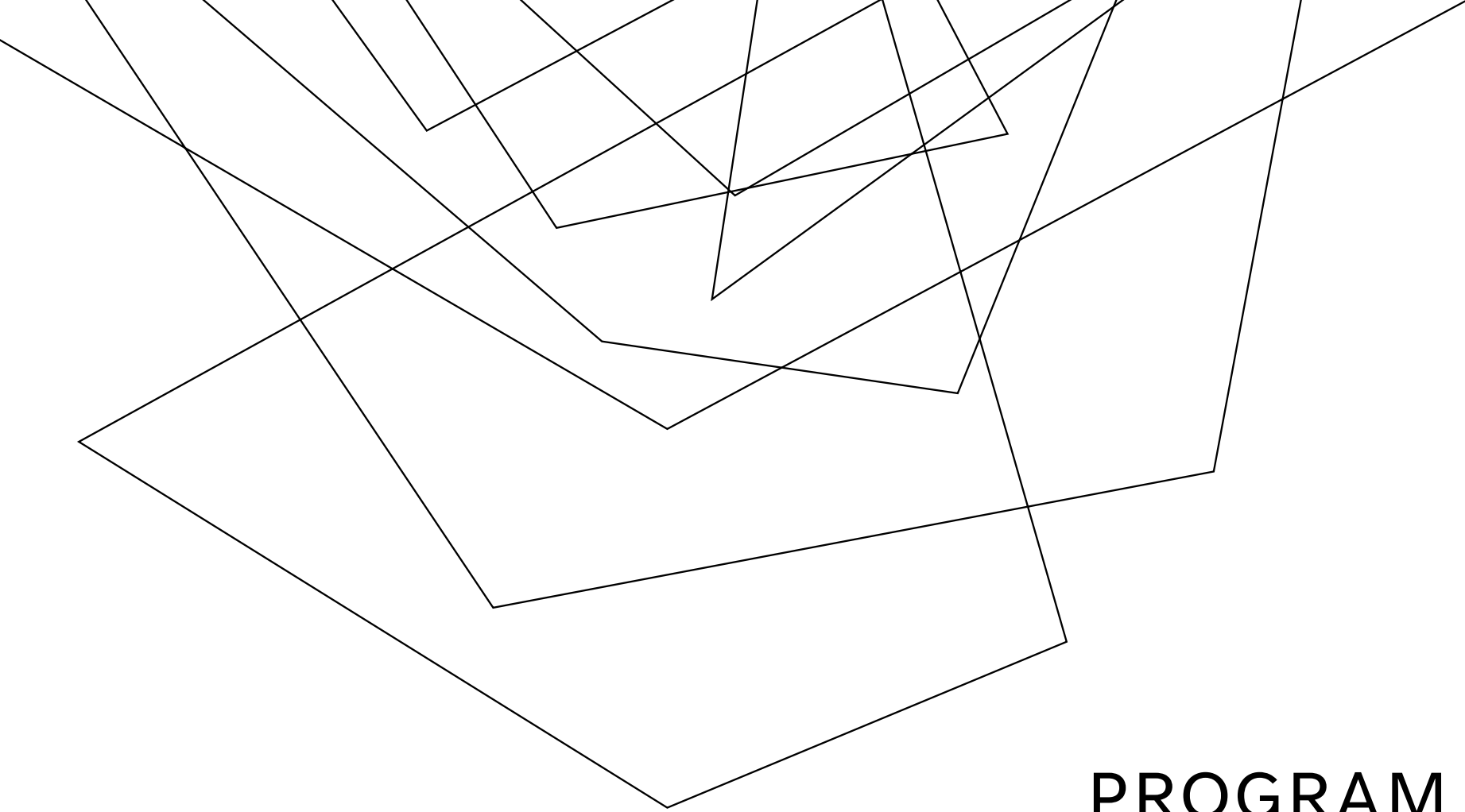
Our points-to relationships are somewhat contrived

Would a program ever actually have both of these statements?

`*a = b;`

`*a = *b;`



Abstract geometric lines in the top-left corner of the slide, consisting of several thin black lines forming overlapping, irregular polygons and triangles.

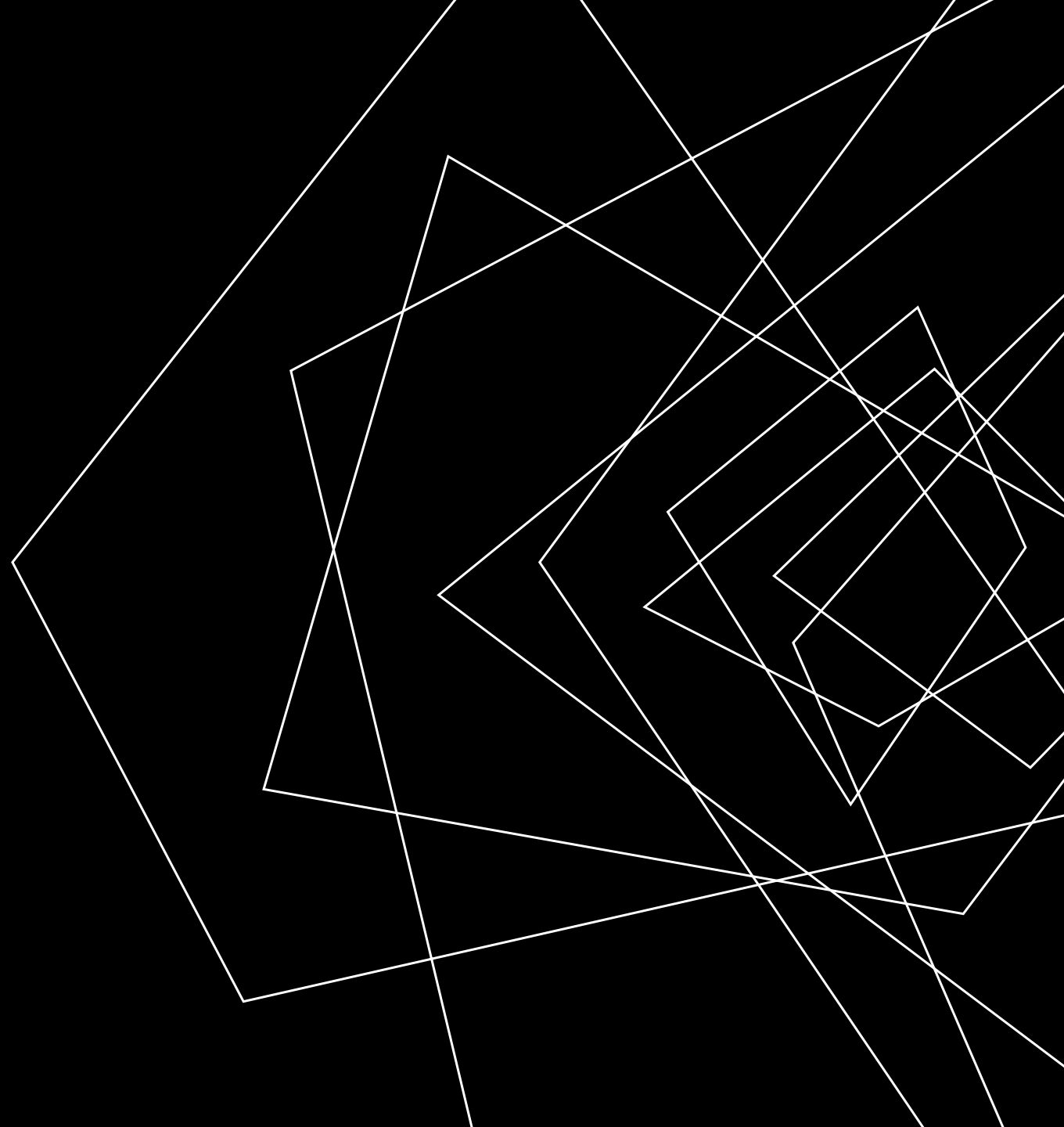
PROGRAM INSTRUMENTATION

EECS 677: Software Security Evaluation

Drew Davidson

LECTURE OUTLINE

- Steensgard's Analysis
- Static Analysis Underview
- Program Instrumentation



OVERHEAD

ANDERSEN'S ANALYSIS

WORST CASE: CUBIC TIME

That's not great!

Most of the time is spent in re-analyzing constraints to get to a fixpoint

OPTIMIZATION: CYCLE ELIMINATION

Detect and collapse SCCs in the points-to relation



A MORE-EFFICIENT POINTS-TO

STEENSGARD'S ANALYSIS

RETURN AGAIN TO OUR ANCIENT WISDOM

Simpler abstractions reach fixpoints faster



ANCIENT PROVERBS
FROM AROUND THE WORLD

A MORE-EFFICIENT POINTS-TO

STEENSGARD'S ANALYSIS

RETURN AGAIN TO OUR ANCIENT WISDOM

Simpler abstractions reach fixpoints faster

STEENGARD'S ANALYSIS

Limit the points-to graph nodes to have outdegree ≤ 1

Simplifies many points-to constraints from subsets to equalities

Achieves near-linear performance

You can only point to 1 node

If you need to point to > 1 node, merge the “pointees”



STEENGARD'S ALGORITHM

AN EFFICIENT OVER-APPROXIMATION

IN PRACTICE *Andersen's*
Step 1

List pointer-related operations

Step 2 *equality*

Induce set of ~~subset~~ constraints

Step 3

Solve system of constraints

REACHABILITY FORMULATION

Step 1

List pointer-related operations

Step 2 *1-out*

Saturate points-to graph

Step 3

Compute node reachability

Andersen's

Assignment	Constraint	Meaning
$a = \&b$	$a \supseteq \{b\}$	$\text{loc}(b) \in \text{pts}(a)$
$a = b$	$a \supseteq b$	$\text{pts}(a) \supseteq \text{pts}(b)$
$a = *b$	$a \supseteq *b$	$\forall v \in \text{pts}(b). \text{pts}(a) \supseteq \text{pts}(v)$
$*a = b$	$*a \supseteq b$	$\forall v \in \text{pts}(a). \text{pts}(v) \supseteq \text{pts}(b)$

Steenggaard's

Assignment	Constraint	Meaning
$a = \&b$	$a \supseteq \{b\}$	$\text{loc}(b) \in \text{pts}(a)$
$a = b$	$a = b$	$\text{pts}(a) = \text{pts}(b)$
$a = *b$	$a = *b$	$\forall v \in \text{pts}(b). \text{pts}(a) = \text{pts}(v)$
$*a = b$	$*a = b$	$\forall v \in \text{pts}(a). \text{pts}(v) = \text{pts}(b)$

EQUALITY CONSTRAINTS

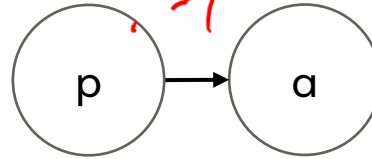
STEENSGARD'S ANALYSIS

Constraint type	Assignment	Constraint	Meaning
Base	$a = \&b$	$a \supseteq \{b\}$	$\text{loc}(b) \in \text{pts}(a)$
Simple	$a = b$	$a = b$	$\text{pts}(a) = \text{pts}(b)$
Complex	$a = *b$	$a = *b$	$\forall v \in \text{pts}(b). \text{pts}(a) = \text{pts}(v)$
Complex	$*a = b$	$*a = b$	$\forall v \in \text{pts}(a). \text{pts}(v) = \text{pts}(b)$

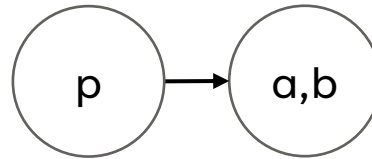
EQUALITY CONSTRAINTS

STEENSGARD'S ANALYSIS

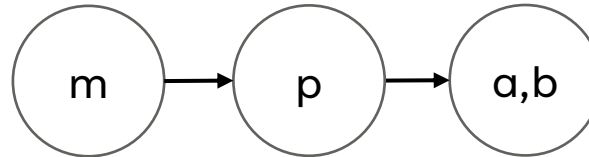
$p = \&a$



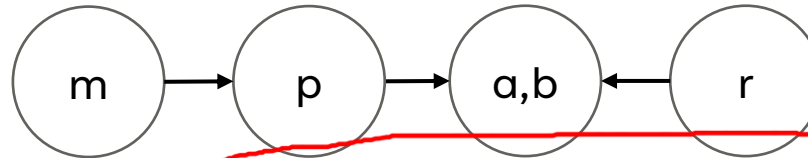
$p = \&b$



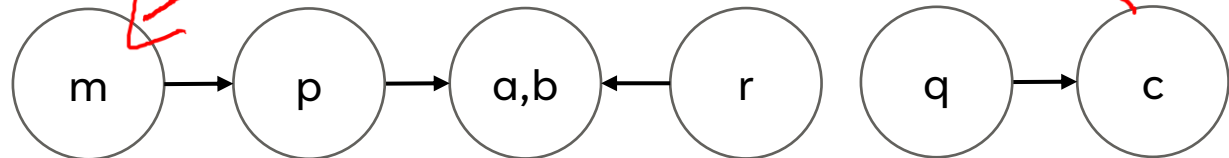
$m = \&p$



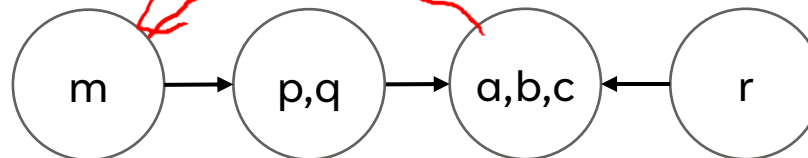
$r = *m$



$q = \&c$



$m = \&q$

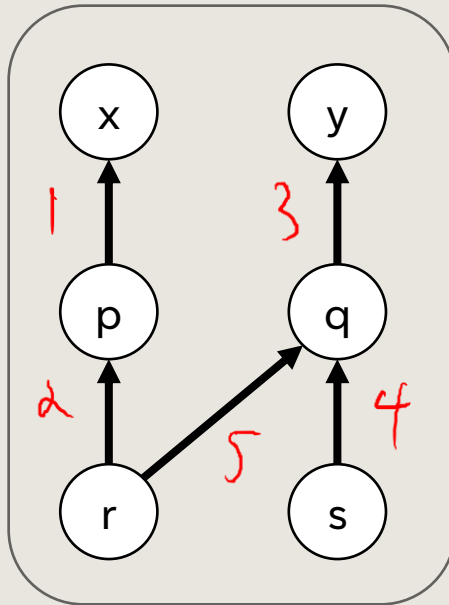


EQUALITY CONSTRAINTS

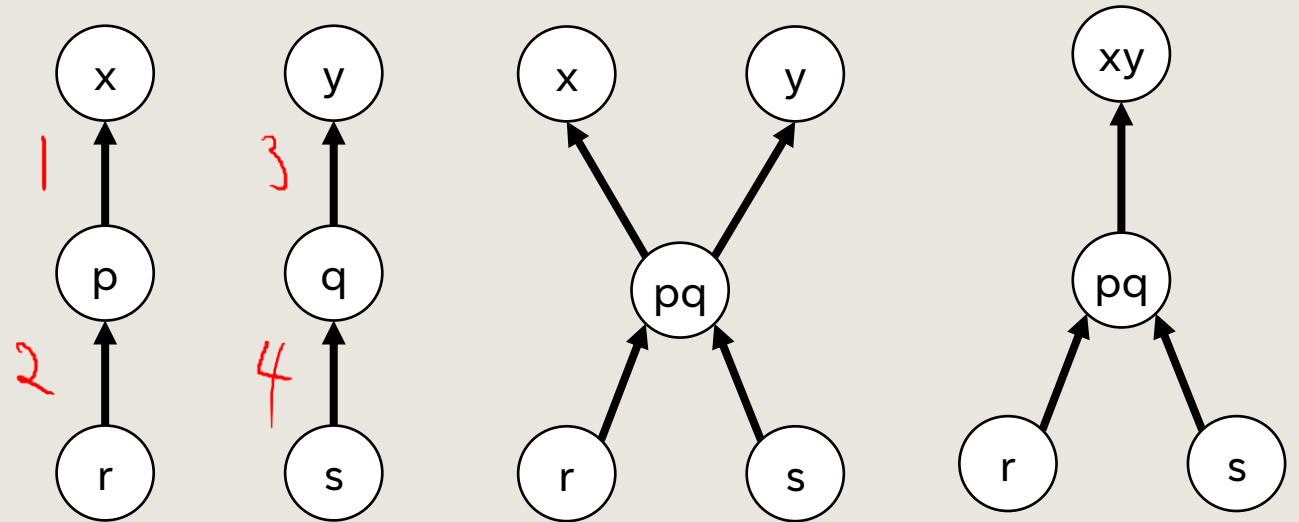
STEENSGARD'S ANALYSIS

$p = \&x$
 $r = \&p$
 $q = \&y$
 $s = \&q$
 $r = s$

Andersen's



Steensgard's



THAT'S POINTS-TO!

STEENSGARD'S ANALYSIS

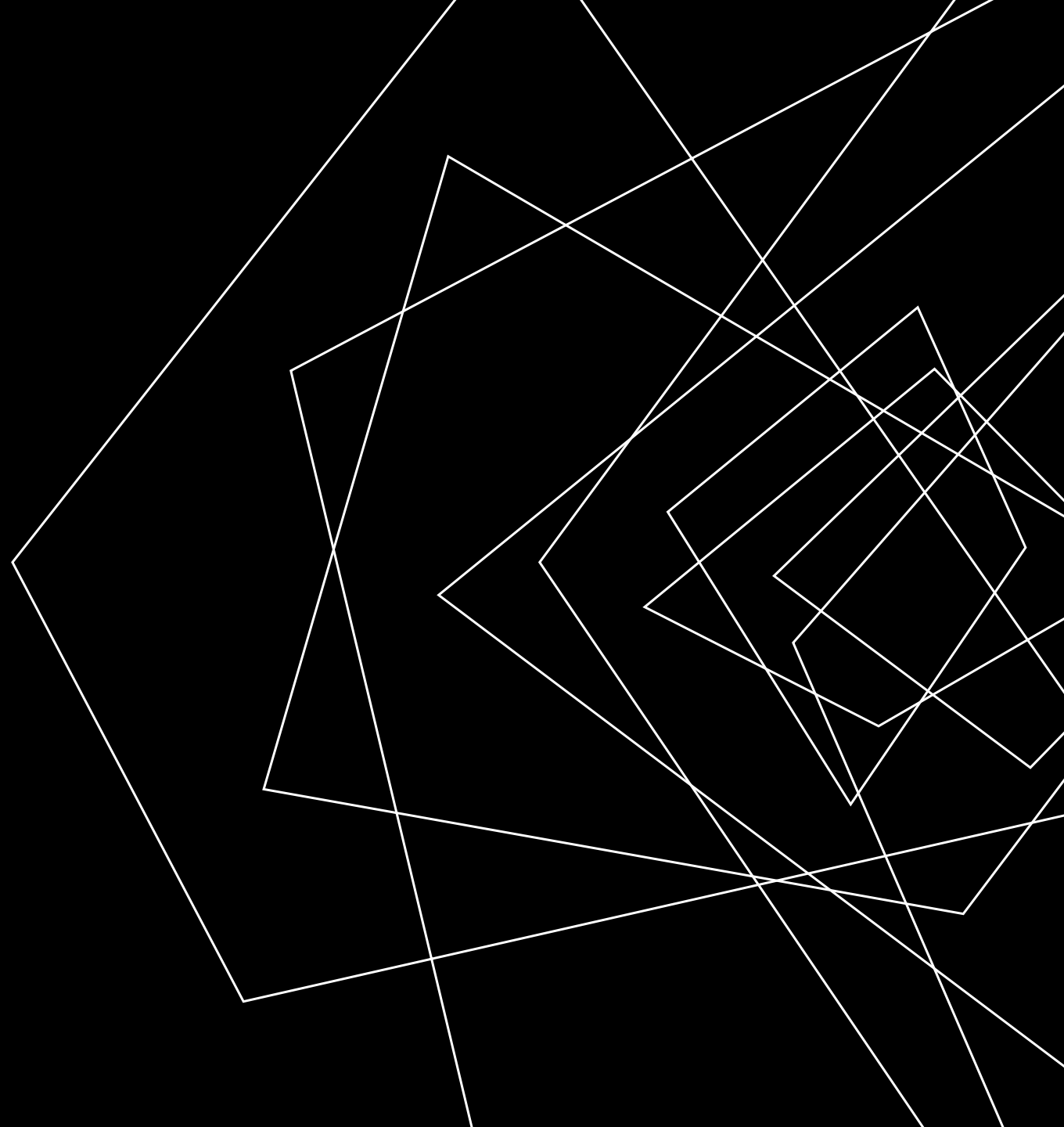
AN ADDITIONAL OVERLAY ON DATAFLOW

Dataflow facts also flow to aliases

When dereferencing a pointer, consider only pointed-to objects

LECTURE OUTLINE

- Steensgard's Analysis
- Static Analysis Underview
- Program Instrumentation



STATIC ANALYSIS READY TO GO!

STATIC ANALYSIS UNDERVIEW

DATAFLOW ANALYSIS CAN BE ADOPTED
FOR CHECKING A VARIETY OF SECURITY /
CORRECTNESS PROPERTIES

Forms the basis of a lot of static analysis!

Applicable for a variety of analysis goals

- Security leak detection
- Vulnerable program state detection
- Program understanding



STATIC ANALYSIS: BENEFITS

STATIC ANALYSIS UNDERVIEW

“THE ANALYST’S SIEVE”

Focus your attention on potential issues

NON-INTERACTIVE!

Can run in the background

Abstraction obviates need for input

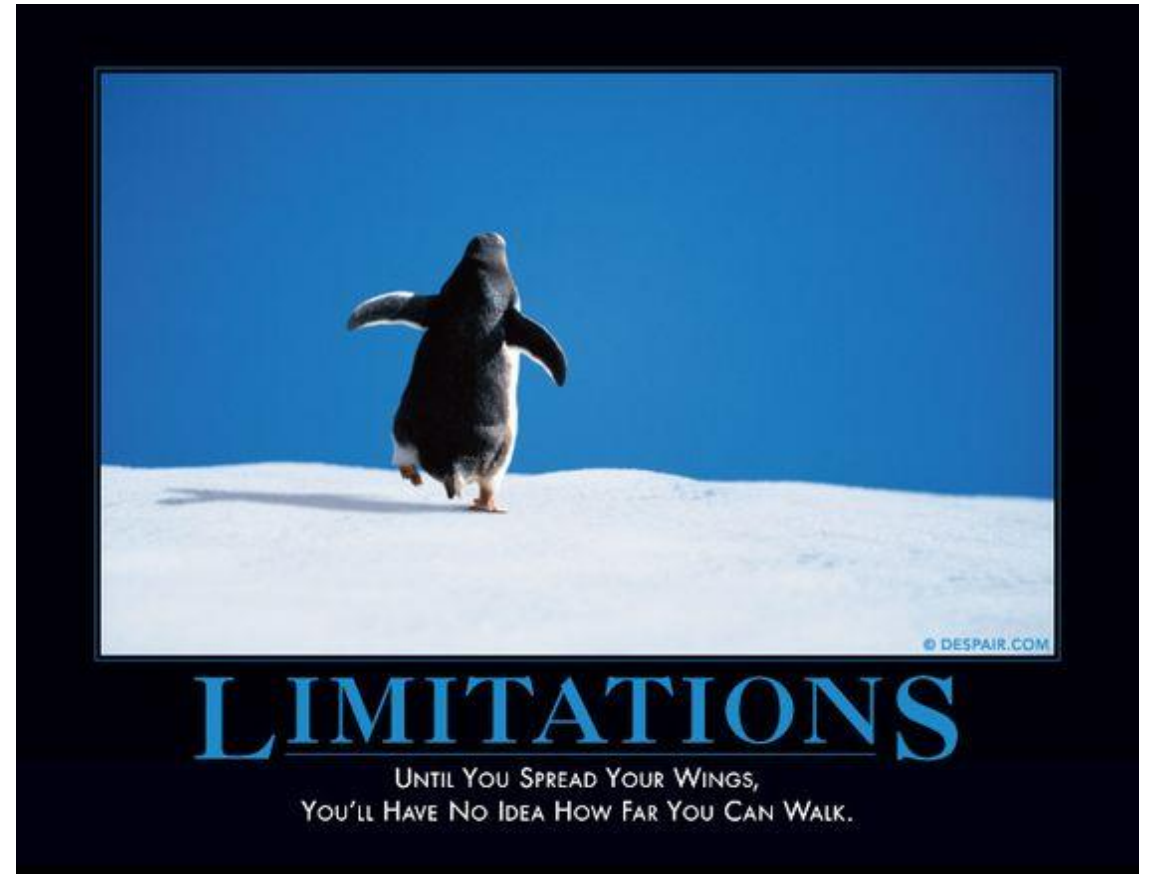


LIMITS OF STATIC ANALYSIS

PROGRAM INSTRUMENTATION: BASIC IDEA

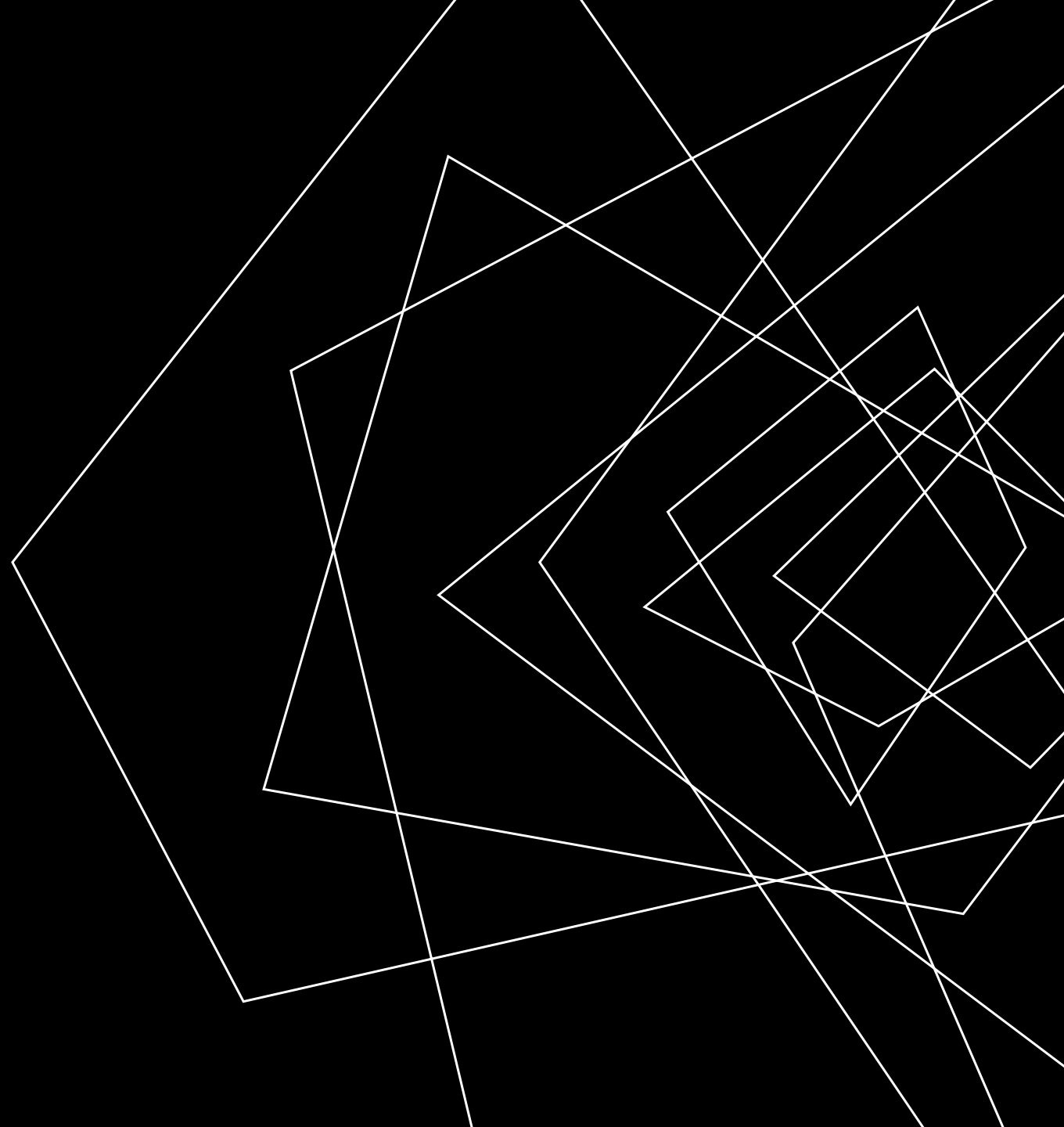
PRACTICAL ISSUES

- Unsoundness of bug finding / incompleteness of program verification
- Scalability
- Significant engineering effort
- Findings may not be super actionable



LECTURE OUTLINE

- Steensgard's Analysis
- Static Analysis Underview
- Program Instrumentation



REVISING DYNAMIC ANALYSIS

PROGRAM INSTRUMENTATION: BASIC IDEA

GIVING UP ON COMPLETE BUG-FINDING

- Finding bugs (even “low-hanging fruit”) is useful!

BENEFITS

- Scalability
- Sound bug finding

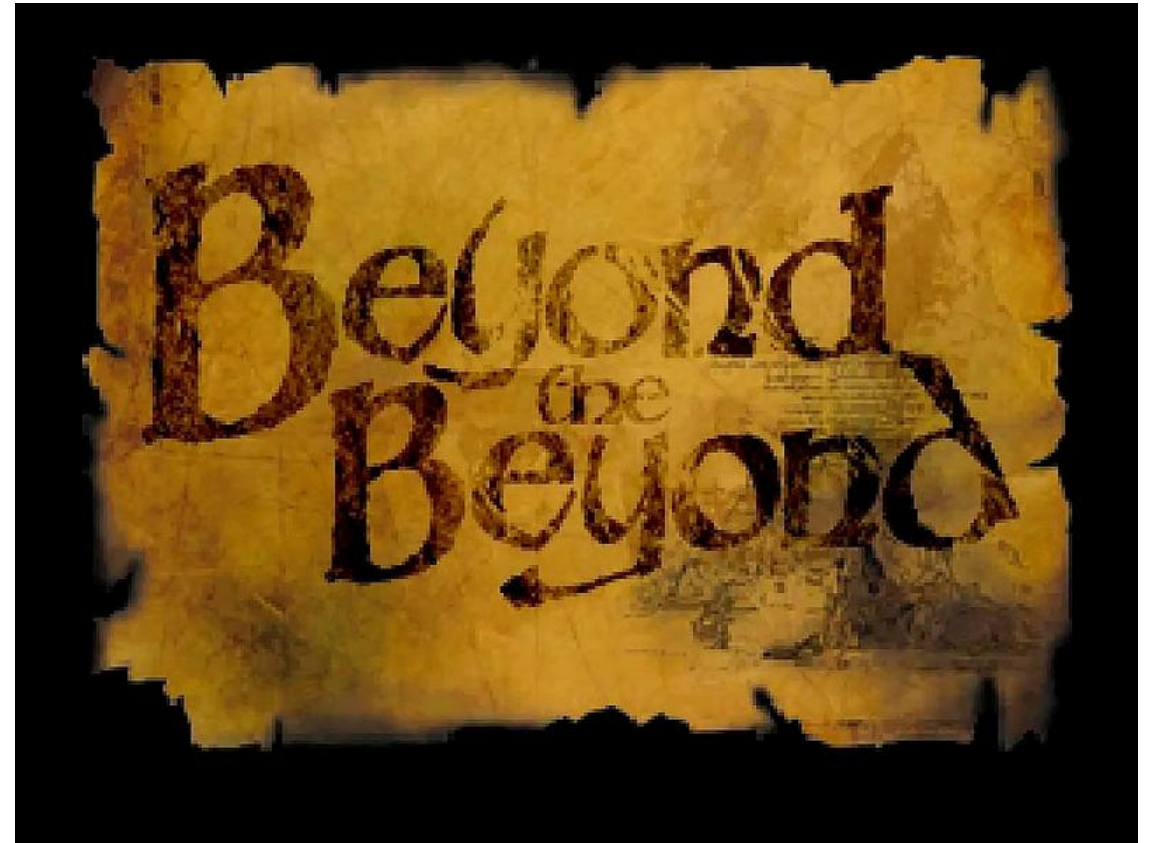


BEYOND TESTING

PROGRAM INSTRUMENTATION: BASIC IDEA

LIMITATIONS OF “PLAIN” TESTING

- Property may not be immediately observable from output alone
- The circumstances under which the issue occurs may not be obvious

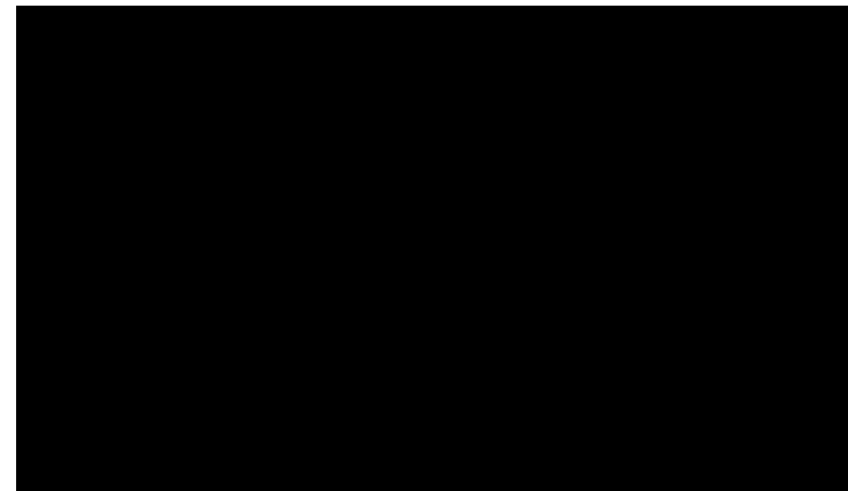


PROGRAM INSTRUMENTATION

PROGRAM INSTRUMENTATION: BASIC IDEA

WRITE CODE INTO THE EXECUTABLE
TO GATHER INFORMATION

Addresses both of the previous issues – can
report upon program state and even program
path

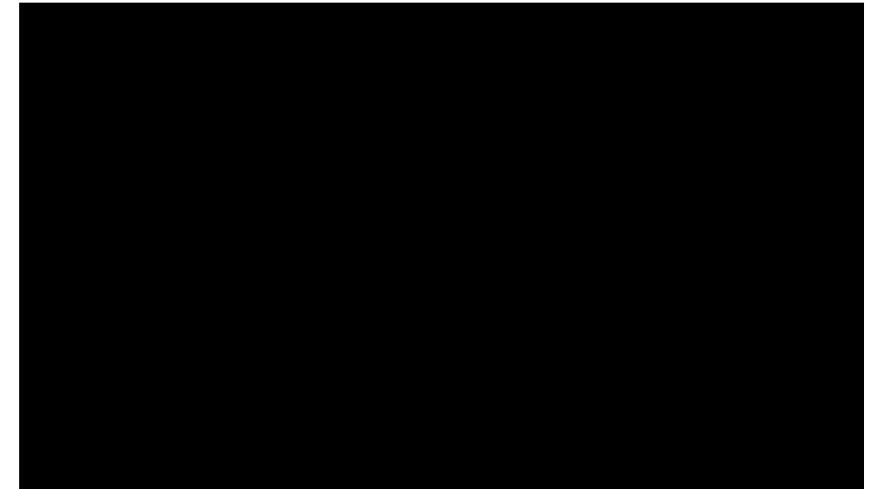


EXAMPLE: LLVM INSTRUMENTATION

PROGRAM INSTRUMENTATION: BASIC IDEA

WRITE CODE INTO THE EXECUTABLE
TO GATHER INFORMATION

Addresses both of the previous issues – can
report upon program state and even program
path



INSERTING PROGRAM PROBES

PROGRAM INSTRUMENTATION: BASIC IDEA

INSERT CHECKS / REPORTS INTO THE ANALYSIS TARGET

Addresses both of the previous issues – can report upon program state and even program path

A NEW CONCERN – THE EFFICIENCY OF THE (INSTRUMENTED) PROGRAM

Potential slowdown on each program path

OLD CONCERN – THE EFFICIENCY OF PLACEMENT ANALYSIS

Somewhat limited by the information the probes can report



EXAMPLE: CODE COVERAGE

PROGRAM INSTRUMENTATION: BASIC IDEA

```
b cc qtoi (c'4);  
a/b;
```



EXAMPLE: CODE COVERAGE

PROGRAM INSTRUMENTATION: BASIC IDEA

COUNTING HOW MANY TIMES CERTAIN BEHAVIORS OF THE PROGRAM ARE EXERCISED

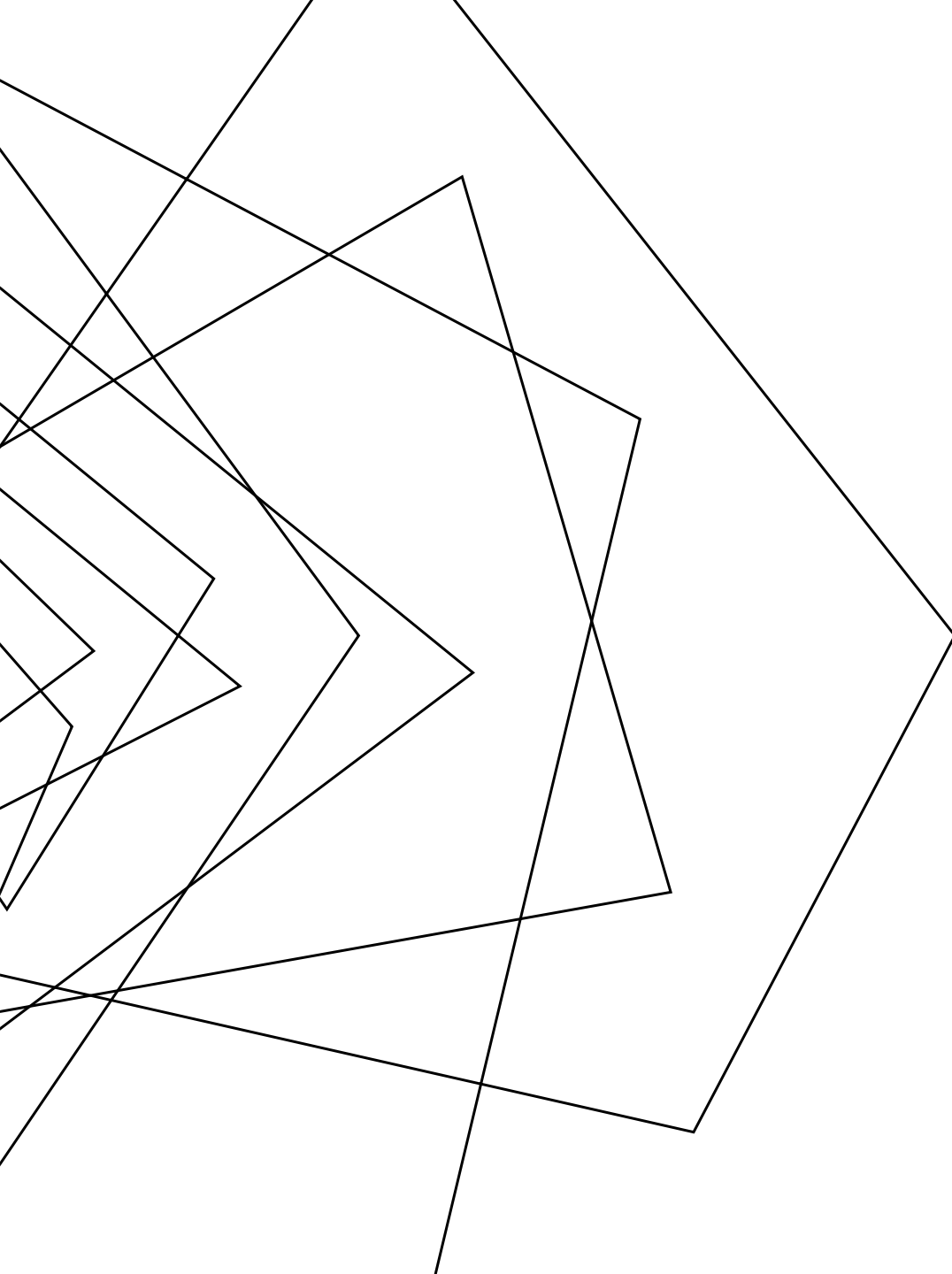
Why is this useful? (Placing sanitizers)

THIS ACTUALLY TURNS OUT TO BE A LITTLE BIT TRICKY!

Actually turns out to be a little bit tricky!

We'll describe some of the issues / solution as per Ball and Larus, '96





WRAP-UP

WE'VE BEGUN TO CONSIDER A WAY TO
MOVE BEYOND STATIC ANALYSIS WHILE
USING OUR EXISTING TOOLS: PROGRAM
INSTRUMENTATION